Proper complex random processes

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Abstract In this paper we study properties of stationary proper complex random process with stable correlation functions. Estimates are obtained for distribution of supremum of modulus of these processes and normes in spaces $L_p$ on finite and infinite intervals.

Keywords complex random process, stationary Gaussian proper complex random process, stable correlation function, square Gaussian random process.

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1. Introduction

This article deals with complex random processes which are one of the most important generalizations of the concept of random process (see [2, 12]). The complex random processes are especially relevant when the narrow-banded processes are investigated. These processes are exploited as models of complex amplitudes of quasi-harmonic oscillations or waves in radiophysics and optics [1]. In this article we presented results of investigation of properties of complex random processes which are useful when solving problems in the listed above areas. Conditions for existence of proper complex random processes are described in [12, 2]. In this article we investigate stationary proper complex random processes, stationary proper complex random processes with stable correlation function. Some results for properties of stable correlation function are presented in paper [11]. In this article some properties of square Gaussian random variables and process are presented (for more results see, for example, [3, 7, 8]). Also, in this paper estimates of distributions of functionals from the module of stationary Gaussian proper random processes are obtained (for more results see, for example, [13, 6, 10]). Theorems, which describe behavior of the module of stationary proper complex random process at infinity are developed.

The content of the article is as follows. In Section 2 we introduce the basic definitions related to the complex random processes. Stationary proper complex random processes are introduced and discussed in Section 3. In the next Section 4, we deal with properties of square Gaussian random variables and processes. Section 5 is related to estimates of distributions of some functions from the module of stationary Gaussian proper complex random process. And in the last Section 6 behavior of the module of stationary proper complex random process at infinity is studied.

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2. Proper Complex Random Process

**Definition 2.1.** A random process of the form $X(t) = X_c(t) + iX_s(t)$, $t \in \mathbb{R}$, where $X_c(t)$ and $X_s(t)$ are real-valued random processes ($c$ – cosine, $s$ – sine), is called complex random process (see book [2] and paper [12]).

**Remark 2.1.** In this paper we will consider centered random processes, that is

$$EX(t) = EX_c(t) = EX_s(t) = 0.$$  

**Definition 2.2.** The function

$$r(\tau, t) = EX(t + \tau)X(t) = EX_c(t + \tau)X_c(t) + EX_s(t + \tau)X_s(t) + i(EX_c(t + \tau)X_s(t) - EX_s(t + \tau)X_c(t))$$

is called correlation function of the process $X(t)$.

The function

$$\hat{r}(\tau, t) = EX(t + \tau)X(t) = EX_c(t + \tau)X_c(t) - EX_s(t + \tau)X_s(t) + i(EX_c(t + \tau)X_s(t) + EX_s(t + \tau)X_c(t))$$

is called pseudo correlation function of the process $X(t)$.

**Definition 2.3.** A complex random process $X(t)$ is called proper complex random process (PCR process), if the pseudo correlation function of this process is equal to zero, $\hat{r}(t + \tau, \tau) = 0$, that is when conditions

$$EX_c(t + \tau)X_c(t) = EX_s(t + \tau)X_s(t),$$  

$$EX_c(t + \tau)X_s(t) = -EX_s(t + \tau)X_c(t).$$  

hold true.

**Remark 2.2.** Conditions under which PCR processes exist are described in book [2] and paper [12].

**Definition 2.4.** [12] A proper complex random process is called (wide sense) stationary if for all $\tau, t \in \mathbb{R}$ the following relation holds true

$$r(\tau, t) = EX(t + \tau)X(t) = r(\tau).$$

**Remark 2.3.** In the case where PCR-process $X(t)$ is stationary we can write the following relations

$$EX_c(t + \tau)X_c(t) = EX_s(t + \tau)X_s(t) = \frac{1}{2} \text{Re} r(\tau),$$  

$$EX_c(t + \tau)X_s(t) = \frac{1}{2} \text{Im} r(\tau).$$

**Definition 2.5.** A complex random process $X(t) = X_c(t) + iX_s(t)$ is called Gaussian if the real-valued random processes $X_c(t)$ and $X_s(t)$ are jointly Gaussian processes.

3. Stationary PCR-processes with stable correlation functions

**Definition 3.1.** The correlation function $r(\tau, \tau) \in \mathbb{R}$ of stationary proper complex random process is called stable correlation function if it can be represented in the form

$$r(\tau) = \sigma^2 \exp \left\{ -c|\tau|^\alpha \left( 1 + i\beta \frac{\tau}{|\tau|} \omega(\tau, \alpha) \right) \right\}$$

where $\sigma^2, c, \beta, \alpha$ are real-valued constants, such that $\sigma^2 > 0, c > 0, |\beta| \leq 1, 0 \leq \alpha \leq 2$,

$$\omega(\tau, \alpha) = \left\{ \begin{array}{ll} \frac{\pi \alpha}{2}, & 0 \leq \alpha \leq 2, \alpha \neq 1, \\ \frac{\pi}{2} \log |\tau|, & \alpha = 1. \end{array} \right.$$
Remark 3.1. The function $r(\tau)$ is non-negative definite, since $r(\tau)$ is the characteristic function of a stable random variable $\xi$, $E\xi = 0$, in the case where $\sigma^2 = 1$ (see [11, p.169]).

Definition 3.2. A stationary PCR process is called proper stationary random complex process with stable covariance function (stationary SPCR process) if

$$EX(t + \tau)\overline{X}(t) = r(\tau)$$

where the function $r(\tau)$ is given by formula (5).

Remark 3.2. For the proper stationary random complex process $X(t) = X_c(t) + iX_s(t)$, $EX(t) = 0$, with stable covariance functions the following relations hold true

$$EX_c(t + \tau)X_c(t) = \frac{1}{2} \Re r(\tau) = \frac{\sigma^2}{2} \exp \{-c|\tau|^a\} \cos (c|\tau|^a \beta \frac{\tau}{|\tau|} \omega(\tau, \alpha))$$

$$EX_s(t + \tau)X_s(t) = \frac{1}{2} \Im r(\tau) = -\frac{\sigma^2}{2} \exp \{-c|\tau|^a\} \sin (c|\tau|^a \beta \frac{\tau}{|\tau|} \omega(\tau, \alpha)),$$

$$\Re r(-\tau) = \Re r(\tau).$$

4. Square Gaussian random variables and processes

In this section we propose definitions and some properties of square Gaussian random variables and processes.

Definition 4.1. [3, 7] Let $(T, \rho)$ be a metric space and let $\Theta = \{\xi(t), t \in T\}$, $E\xi(t) = 0$, be a family of jointly Gaussian random variables (e.g. $\xi = \{\xi(t), t \in T\}$ is a Gaussian random process). The space of square Gaussian random variable ($SG_{\Theta}(\Omega)$) is such a space that any element $\eta \in SG_{\Theta}(\Omega)$ can be presented in the form

$$\eta = \xi^\top A \xi - E(\xi^\top A \xi),$$

where $\xi^\top = (\xi_1, \xi_2, \ldots, \xi_n)$, $\xi_k \in \Theta, k = 1, 2, \ldots, n$ and $A$ is a real-valued matrix, or the element $\eta \in SG_{\Theta}(\Omega)$ is the mean square limit of a sequence of random variables of the form (9):

$$\eta = l.i.m. \left( \xi_n^\top A_n \xi_n - E(\xi_n^\top A \xi_n) \right).$$

Definition 4.2. A random process $\eta = \{\eta(t), t \in T\}$ is called square Gaussian process if the family of random variables $\eta = \{\eta(t), t \in T\}$ forms the space of square Gaussian random variables.

The next theorem is a modification of Theorem 3.2 from the book [7].

Theorem 4.1

Let $X = \{X(t), t \in [a, b]\}$ be a separable square Gaussian random process and let the condition

$$\sup_{|t-s| \leq h} \left(Var \left( X(t) - X(s) \right) \right)^{1/2} \leq C h^{\beta}$$

holds true for $\beta \in (0, 1], C > 0$. Then for all integer $M > 1$ and all

$$x > \frac{\sqrt{2} \gamma_0 M}{\beta \max \left( 1, \left( \frac{b-a}{2} \right)^{\beta} \frac{C}{\gamma_0} \right)^{\frac{1}{\beta}}}$$
where \( \gamma_0 = \sup_{a \leq t \leq b} (\text{Var} X(t))^{1/2} \), the tail of distribution of the process \(|X(t)|\) can be estimated in the following way

\[
P \left\{ \sup_{t \in [a, b]} |X(t)| > x \right\} \leq 4e^{M \beta} \exp \left\{ -\frac{x}{\sqrt{2} \gamma_0} \right\} \left( \frac{\beta \cdot x}{\sqrt{2} \gamma_0 M} \right)^{\frac{M}{2}} \left( 1 + \frac{\sqrt{2} x}{\gamma_0} \right)^{1/2}. \tag{11} \]

**Theorem 4.2**

Let \( X = \{X(t), t \in [a, b]\} \), where \(-\infty < a < b \leq \infty\), be a measurable square-Gaussian random process. Let the Lebesgue integral

\[
\int_a^b \left( E(X(t))^2 \right)^{p/2} dt
\]

be well defined for \( p \geq 1 \). Then the integral

\[
\int_a^b |X(t)|^p dt
\]

exists with probability 1 and for all

\[
\varepsilon \geq \left( \frac{p}{\sqrt{2}} + \sqrt{\left( \frac{p}{2} + 1 \right) p} \right) C_p,
\]

where

\[
C_p = \int_a^b \left( E(X(t))^2 \right)^{p/2} dt,
\]

the following inequality holds true

\[
P \left\{ \int_a^b |X(t)|^p dt > \varepsilon \right\} \leq 2 \sqrt{1 + \frac{\varepsilon^{1/p}}{C_p}} \exp \left\{ -\frac{\varepsilon^{1/p}}{\sqrt{2} C_p^{1/p}} \right\}. \tag{12} \]

**Corollary 4.1**

Let assumptions of Theorem 4.2 be satisfied. Then for

\[
u \geq \left( \frac{p}{\sqrt{2}} + \sqrt{\left( \frac{p}{2} + 1 \right) p} \right) C_p^{1/p}
\]

the following inequality holds true

\[
P \left\{ \|X(t)\|_{L_p(a, b)} > \nu \right\} \leq 2 \sqrt{1 + \frac{\nu \sqrt{2}}{C_p^{1/p}}} \exp \left\{ -\frac{\nu}{\sqrt{2} C_p^{1/p}} \right\}. \tag{13} \]

5. Estimation of distribution of some functionals from module of stationary Gaussian PCR-processes

**Theorem 5.1**

Let \( X = \{X(t), t \in [a, b]\} \) be a Gaussian SPCR process and let \(|X(t)| = (X_e^2(t) + X_s^2(t))^{1/2}\). Then for

\[
u \geq \left( \frac{p}{\sqrt{2}} + \sqrt{\left( \frac{p}{2} + 1 \right) p} \right) \sigma^2 (b - a)^{1/p}
\]

the following inequality holds
\[
P \left\{ \left\| X(t)^2 - \sigma^2 \right\|_{\mathcal{L}_p([a,b])} > u \right\} \leq 2 \sqrt{1 + \frac{u \sqrt{2}}{(b-a)^{1/p} \sigma^2}} \cdot \exp \left\{ -\frac{u}{\sqrt{2}(b-a)^{1/p} \sigma^2} \right\}. \quad (14)
\]

**Proof**
The proof of this theorem follows from inequality (13). Indeed it follows from (6), that
\[
EX_c^2(t) = E(X_s(t))^2 = \frac{1}{2} R(r(0)) = \frac{\sigma^2}{2}.
\]
Therefore \(E|X(t)|^2 = \sigma^2\) and
\[
E \left( |X(t)|^2 - \sigma^2 \right)^2 = E \left( |X(t)|^2 - E|X(t)|^2 \right)^2 = E|X(t)|^4 - \left( E|X(t)|^2 \right)^2 = E|X(t)|^4 - \sigma^4. \quad (15)
\]
Suppose that \((X_1, X_2, X_3, X_4)\) is a zero-mean Gaussian vector. Then we have:
\[
E(X_1X_2X_3X_4) = E(X_1X_2)E(X_3X_4) + E(X_1X_3)E(X_2X_4) + E(X_1X_4)E(X_2X_3).
\]
This equality is called Isserlis formula (see, for example [3, p.228]. Making use of this formula and relations (3), (4) we can write
\[
E|X(t)|^4 = E \left( |X_c(t)|^2 + |X_s(t)|^2 \right)^2 = E|X_c(t)|^4 + E|X_s(t)|^4 + 2E|X_c(t)|^2|X_s(t)|^2,
\]
\[
E|X_c(t)|^4 = 3 \left( E|X_c(t)|^2 \right)^2 = 3 \frac{\sigma^4}{4} = E|X_s(t)|^4;
\]
\[
E(|X_c(t)|^2|X_s(t)|^2) = E|X_c(t)|^2 E|X_s(t)|^2 + 2(EX_c(t)X_s(t))^2.
\]
Since
\[
E(X_c(t)X_s(t)) = \frac{1}{2} \text{Im}(r(0)) = 0
\]
we have
\[
E|X(t)|^4 = 2\sigma^4.
\]
It follows from (15) that
\[
E \left( (X(t))^2 - \sigma^2 \right)^2 = \sigma^4
\]
and
\[
\int_a^b E \left( |X(t)|^2 - \sigma^2 \right)^{\frac{5}{2}} dt = \sigma^2 p(b-a).
\]
Now (14) follows from (13). \(\square\)

**Theorem 5.2**
Let \(X = \{X(t), t \in [a,b]\}\) be a Gaussian SPCR process and let
\[
|X(t)| = (X_c^2(t) + X_s^2(t))^{1/2}.
\]
If \(X(t)\) is a separable process, then for all integer \(M > 1\) and all
\[
u > \frac{2\sqrt{2} \sigma^2 M}{\alpha} \left( \max \left( 1, \frac{(b-a)}{2} \right)^{\frac{a}{2}} 2\sqrt{c} \right)^{\frac{1}{\pi - \tau}}
\]

we have
\[
P \left\{ \sup_{a \leq t \leq b} \left| (X(t))^2 - \sigma^2 \right| > x \right\} \leq 4e^{2(M+1)} \exp \left\{ -\frac{x}{\sqrt{2\sigma^2}} \right\} \left( \frac{\alpha x}{2\sqrt{2\sigma^2}M} \right)^{\frac{2\alpha}{\sigma^2}} \left( 1 + \frac{\sqrt{2}x}{\sigma^2} \right)^{1/2}
\] (16)

**Proof**

The statement of this Theorem follows from Theorem 4.1. In our case \( \gamma_0 = \sigma^2 \). 

In order to apply Theorem 4.1 to the process \( |X(t)|^2 = (X^2_c(t) + X^2_s(t))^2 \) we have to estimate \( E(Y(t) - Y(s))^2 \), where \( Y(t) = |X(t)|^2 - \sigma^2 \).

It is easy to see that
\[
E(Y(t) - Y(s))^2 = E(X^2_c(t) + X^2_s(t) - X^2_s(s) - X^2_s(s))^2 =
\]
\[
= E(X^2_c(t) - X^2_s(s) + X^2_s(t) - X^2_s(s))^2 =
\]
\[
= E(X^2_c(t) - X^2_s(s))^2 + E(X^2_s(t) - X^2_s(s))^2 + 2E(X^2_c(t) - X^2_s(s)) E(X^2_s(t) - X^2_s(s)) =
\]
\[
w_1 + w_2 + w_3,
\]
\[
w_1 = E(X_c(t))^4 + E(X_c(s))^4 - 2E(X_c(t)X_c(s))^2,
\]
\[
E(X_c(t))^4 = E(X_c(s))^4 = \frac{3}{4}\sigma^4,
\]
\[
E(X_c^2(t)X_c^2(s)) = E(X_c(t))^2 E(X_c(s))^2 + 2E(X_c(t)X_c(s))^2 =
\]
\[
= \frac{\sigma^4}{4} + 2 \left( \frac{1}{2} \operatorname{Re}(r(t-s))^2 \right).
\]

Therefore
\[
w_1 = \sigma^4 - \left( \operatorname{Re}(r(t-s))^2 \right).
\]

Next, we have
\[
w_1 = w_2,
\]
\[
w_1 + w_2 = 2 \left( \sigma^4 - \left( \operatorname{Re}(r(t-s))^2 \right) \right),
\]
\[
\frac{w_3}{2} = E(X^2_c(t)X^2_s(t)) + E(X^2_c(s)X^2_s(s)) - E(X^2_c(s)X^2_s(t)) - E(X^2_c(t)X^2_s(s)).
\]

Since \( \operatorname{Im}(r(0)) = 0 \), then
\[
E(X^2_c(t)X^2_s(t)) = E(X^2_c(t)EX^2_s(t) + 2E(X_c(t)X_s(t))^2 = \frac{\sigma^4}{4} + 2 \left( \frac{1}{2} \operatorname{Im}(r(0)) \right)^2 = \frac{\sigma^4}{4}.
\]

In the same way we can obtain that
\[
E(X^2_c(s)X^2_s(s)) = \frac{\sigma^4}{4},
\]
\[
E(X^2_c(t)X^2_s(s)) = \frac{\sigma^4}{4} + \frac{1}{2} \left( \operatorname{Im}(r(t-s))^2 \right).
\]

Consequently
\[
w_3 = - \left( \left( \operatorname{Im}(r(s-t))^2 + \operatorname{Im}(r(t-s))^2 \right) \right).
\]

Since
\[
\left( \operatorname{Im}(r(s-t))^2 \right) = \left( \operatorname{Im}(r(t-s))^2 \right),
\]
we have
\[
w_3 = -2\left( \operatorname{Im}(r(t-s))^2 \right)
\]
and
\[ E(Y(t) - Y(s))^2 = 2 \left( \sigma^4 - \left( (\text{Re} (r(t-s)))^2 + (\text{Im} (r(t-s)))^2 \right) \right). \]

Since
\[ (\text{Re} (r(t-s)))^2 + (\text{Im} (r(t-s)))^2 = |r(t-s)|^2 = \sigma^4 \exp \{-2c(t-s)\}, \]
\[ = \left| \cos \left( -c|\tau|^\alpha \left| \frac{\beta(t-s)}{|t-s|^2} w(t, \alpha) \right| \right) + i \sin \left( -c|\tau|^\alpha \left| \frac{\beta(t-s)}{|t-s|^2} w(t, \alpha) \right| \right) \right|^2 = \sigma^2 \exp \{-|t-s|_{c} \}, \]
we get the following estimate
\[ E(Y(t) - Y(s))^2 = 2\sigma^4 (1 - \exp \{-2c|t|^\alpha\}) \leq 4\sigma^4 c|t|^\alpha. \]
Consequently \( \beta = \frac{\alpha}{2} \) and \( C = 2\sigma^2 \sqrt{\epsilon} \). Therefore (16) follows from (11).

6. Behavior of the module of stationary PCR-process at infinity

**Theorem 6.1**

Let \( X = \{X(t), t \in (-\infty, \infty)\} \) be a measurable Gaussian SPCR process, let \( |X(t)| = (X_0^2(t) + X_s^2(t))^{1/2} \) and let \( Y(t) = |X(t)|^2 - E(X(t))^2 = |X(t)|^2 - \sigma^2 \). Let \( c(t), t \in R \) be a function such that
\[ \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt < \infty, \quad p \geq 1. \]

Then for
\[ u \geq \left( \frac{p}{\sqrt{2}} + \sqrt{(\frac{p}{2} + 1)} \right) \cdot \sigma^2 \left( \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt \right)^{1/p} \]
the following inequality holds true
\[ P \left\{ \frac{\| (X(t))^2 - \sigma^2 \|}{c(t)} > u \right\} \leq 2 \left\{ 1 + \frac{\sqrt{2}u}{\int_{-\infty}^{\infty} |c(t)|^{-p} \, dt} \exp \left\{ -\frac{u}{\sigma^2 \sqrt{2} \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt} \right\} \right\}. \]

**Proof**

The statement of this Theorem follows from Theorem 4.2 (see Corollary 4.1) if we take
\[ C_p = 2^{-\frac{p}{2}} \sigma^2 \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt. \]

**Corollary 6.1**

Let \( c(t) > 0 \) be an even monotone increasing function for which conditions of Theorem 6.1 are satisfied. Then for all \( t \geq 0 \) the following inequality holds true with probability one:
\[ \left( \int_{-\infty}^{t} \| (X(u))^2 - \sigma^2 \|^{p} \, du \right)^{1/p} \leq c(t) \cdot \xi \]
where $\xi > 0$ is a random variable such that

$$P\left\{ \xi > u \right\} \leq 2 \left[ 1 + \frac{\sqrt{2u}}{\left( \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt \right)^{1/p}} \right] \cdot \exp \left\{ -\frac{u}{\left( \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt \right)^{1/p}} \right\} \cdot \sigma^2,$$

for

$$u \geq \left( \frac{p}{\sqrt{2}} + \sqrt{\left( \frac{p}{2} + 1 \right) p} \right) \cdot \sigma^2 \cdot \left( \int_{-\infty}^{\infty} |c(t)|^{-p} \, dt \right)^{1/p}.$$

**Proof**

The statement of Corollary 6.1 follows from inequalities: $t \geq 0$,

$$\left( \int_{-t}^{t} \left( (X(u))^2 - \sigma^2 \right)^p \, du \right)^{1/p} \leq c(t) \cdot \left( \int_{-t}^{t} \frac{|(X(u))^2 - \sigma^2|}{c(t)^p} \, du \right)^{1/p} \leq c(t) \cdot \left\| \frac{|(X(t))^2 - \sigma^2|}{c(t)} \right\|_{L_p(-\infty, \infty)}.$$

\[ \square \]

**Remark 6.1.** The statement of Corollary 6.1 holds true, for example, for function $c(t) = (1 + |t|^\gamma)$, $\gamma > p$.

**Theorem 6.2**

Let $X = \{X(t), t \in [a, b]\}$ be a separable Gaussian stationary PCR process. Let there exist a sequence $a_k, k = 0, 1, 2, \ldots$ such that $a_k < a_{k+1}, a_k \to \infty$, as $k \to \infty$, $a_0 = 0$ and a function $c(t), t \in [0, \infty)$ such that $c(t) \geq 1, c(t)$ be an even monotone increasing continuous and $c(t) \to \infty$ if $t \to \infty$, $Y(t) = |X(t)|^2 - E(X(t))^2 = |X(t)|^2 - \sigma^2$. Let the condition

$$\varepsilon^* = \frac{2\sqrt{2\sigma^2}}{\alpha} \sup_{0 \leq k \leq \infty} \frac{1}{c(a_k)} \max \left( 1, \left( \frac{a_{k+1} - a_k}{2} \right)^{a/2} \frac{2\sqrt{c}}{\sqrt{2\sigma^2}} \right)^{1/M-1} \leq \infty$$

be satisfied. If for some $\hat{\varepsilon}, \tilde{\varepsilon} \geq \varepsilon^*$, the following series

$$\sum_{k=0}^{\infty} \exp \left\{ -\frac{(c(a_k) - c(a_0)) \hat{\varepsilon}}{\sqrt{2\sigma^2}} \right\} \left( 1 + \frac{\sqrt{2c(a_k)\tilde{\varepsilon}}}{\sigma^2} \right)^{1/2} < \infty,$$

then for all $\varepsilon > \hat{\varepsilon}$

$$P \left\{ \sup_{0 \leq t \leq \infty} \frac{|X(t)|^2 - \sigma^2}{c(t)} > \varepsilon \right\} \leq \exp \left\{ -\frac{\sqrt{2c(a_0)\varepsilon}}{\sigma^2} \right\} \cdot \tilde{\varepsilon} = Z(\varepsilon),$$

where

$$\tilde{\varepsilon} = 4e^{M+1} \cdot \left( \frac{2}{M} \right) \sum_{k=0}^{M} \exp \left\{ -\frac{(c(a_k) - c(a_0)) \hat{\varepsilon}}{\sqrt{2\sigma^2}} \right\} \left( 1 + \frac{\sqrt{2c(a_k)\tilde{\varepsilon}}}{\sigma^2} \right)^{1/2}.$$

**Proof**

For $Y(t) = |X(t)|^2 - \sigma^2$ we have that $Var( Y(t) - Y(s) ) \leq 2\sigma^2 |t - s|^{\tilde{\varepsilon}}$ (see proof of Theorem 5.2). It follows
from Theorem 5.2 that for $M > 1$ and
\[ u > \frac{2\sqrt{2}\sigma^2 M}{\alpha} \left( \max \left( 1, \left( \frac{a_{k+1} - a_k}{2} \right)^2 \right) \right) \] (19)
we have
\[
P \left\{ \sup_{a_k \leq t \leq a_{k+1}} |Y(t)| > u \right\} \leq 4e^{\frac{M+1}{\alpha}} \exp \left\{ -\frac{c(a_k)\varepsilon}{\sqrt{2}\sigma^2} \right\} \left( \frac{\alpha c(a_k)\varepsilon}{2\sqrt{2}\sigma^2 M} \right)^{\frac{2M}{\alpha}} \left( 1 + \frac{\sqrt{2c(a_k)\varepsilon}}{\sigma^2} \right)^{1/2} \] (20)
The following inequality is obvious.
\[
P \left\{ \sup_{t \in [0,\infty)} \frac{|Y(t)|}{c(t)} > \varepsilon \right\} \leq \sum_{k=0}^{\infty} P \left\{ \sup_{a_k \leq t \leq a_{k+1}} |Y(t)| > c(a_k)\cdot\varepsilon \right\}. \] (21)
It follows from (19) and (20) that for $\varepsilon > \frac{2\sigma M}{\alpha c(a_k)} \max \left( 1, \left( \frac{a_{k+1} - a_k}{2} \right)^2 \right) \left( \frac{\sqrt{2\sigma^2}}{\varepsilon} \right)$ we have the following estimate
\[
\varepsilon > \frac{2\sigma M}{\alpha c(a_k)} \max \left( 1, \left( \frac{a_{k+1} - a_k}{2} \right)^2 \right) \left( \frac{\sqrt{2\sigma^2}}{\varepsilon} \right), \] (22)
we have the following estimate
\[
P \left\{ \sup_{a_k \leq t \leq a_{k+1}} |Y(t)| > c(a_k)\varepsilon \right\} \leq 4e^{\frac{M+1}{\alpha}} \exp \left\{ -\frac{c(a_k)\varepsilon}{\sqrt{2}\sigma^2} \right\} \left( \frac{\alpha c(a_k)\varepsilon}{2\sqrt{2}\sigma^2 M} \right)^{\frac{2M}{\alpha}} \left( 1 + \frac{\sqrt{2c(a_k)\varepsilon}}{\sigma^2} \right)^{1/2}. \] (23)
From this inequality (23) and inequality (21) it follows that under condition (22) we have the following estimate
\[
P \left\{ \sup_{a_k \leq t \leq a_{k+1}} \frac{|Y(t)|}{c(t)} > \varepsilon \right\} \leq 4e^{\frac{M+1}{\alpha}} \sum_{k=0}^{\infty} \exp \left\{ -\frac{c(a_k)\varepsilon}{\sqrt{2}\sigma^2} \right\} \left( \frac{\alpha c(a_k)\varepsilon}{2\sqrt{2}\sigma^2 M} \right)^{\frac{2M}{\alpha}} \left( 1 + \frac{\sqrt{2c(a_k)\varepsilon}}{\sigma^2} \right)^{1/2} =
= 4e^{\frac{M+1}{\alpha}} \exp \left\{ -\frac{c(a_0)\varepsilon}{\sqrt{2}\sigma^2} \right\} \sum_{k=0}^{\infty} \exp \left\{ -\frac{(c(a_k) - c(a_0))\varepsilon}{\sqrt{2}\sigma^2} \right\} \left( \frac{\alpha c(a_k)\varepsilon}{2\sqrt{2}\sigma^2 M} \right)^{\frac{2M}{\alpha}} \left( 1 + \frac{\sqrt{2c(a_k)\varepsilon}}{\sigma^2} \right)^{1/2}. \] (24)
It follows from (22) that $\varepsilon > \frac{2\sigma M}{\alpha c(a_k)}$ and $\frac{\alpha c(a_k)}{2\sigma^2} \varepsilon > M \geq 2$.

From inequality (24) under condition (22) we have the following estimate
\[
P \left\{ \sup_{t \in [0,\infty)} \frac{|Y(t)|}{c(t)} > \varepsilon \right\} \leq 4e^{\frac{M+1}{\alpha}} \left( \frac{2}{M} \right)^{\frac{2M}{\alpha}} \exp \left\{ -\frac{c(a_0)\varepsilon}{\sqrt{2}\sigma^2} \right\} \times
\sum_{k=0}^{\infty} \exp \left\{ -\frac{(c(a_k) - c(a_0))\varepsilon}{\sqrt{2}\sigma^2} \right\} \left( 1 + \frac{\sqrt{2c(a_k)\varepsilon}}{\sigma^2} \right)^{1/2}. \] (25)
The function $f(\varepsilon) = \exp \left\{ -\frac{(c(a_k) - c(a_0))\varepsilon}{\sigma} \right\} \left( 1 + \frac{c(a_k)\varepsilon}{\sigma} \right)^{1/2}$ monotonically decreases for $\varepsilon > 0$. For this reason under the condition
\[
\hat{\varepsilon} \geq \varepsilon^* \] (26)
we have that $\forall \varepsilon > \hat{\varepsilon}$
\[
P \left\{ \sup_{t \in [0,\infty)} \frac{|Y(t)|}{c(t)} > \varepsilon \right\} \leq 4e^{\frac{M+1}{\alpha}} \left( \frac{2}{M} \right)^{\frac{2M}{\alpha}} \times
\sum_{k=0}^{\infty} \exp \left\{ -\frac{(c(a_k) - c(a_0))\varepsilon}{\sqrt{2}\sigma^2} \right\} \left( 1 + \frac{\sqrt{2c(a_k)\varepsilon}}{\sigma^2} \right)^{1/2}. \] (27)
Corollary 6.2
Let a function $c(t)$ satisfies conditions of Theorem 6.2. Then with probability one for all $t \in \mathbb{R}$ the following inequality is satisfied

$$|Y(t)| \leq \eta \cdot c(t),$$

where $\eta > 0$ is a random variable such that for $\varepsilon > \hat{\varepsilon}$ the inequality

$$P\{\eta > \varepsilon\} \leq Z(\varepsilon)$$

holds true. For definition of the function $Z(\varepsilon)$ see (18).

Remark 6.2. Condition (17) is satisfied if the series

$$\sum_{k=0}^{\infty} \exp \left\{ -\frac{c(a_k) \hat{\varepsilon}}{2\sigma^2} \right\} (c(a_k))^{2M+\frac{1}{2}}$$

converges. This series converges, for example, in the case where $c(a_k) = \ln (k^d), k > 1$, where $\frac{d\hat{\varepsilon}}{\sqrt{2\sigma^2}} > 1$. A special case is $a_k = k$, that is $c(t) = d \ln (t), d > \frac{\sqrt{2\sigma^2}}{\varepsilon}$ and $t > e$.

7. Conclusions

In the article analysis of properties of proper complex random process is presented. Definitions and some properties of proper stationary random complex process with stable covariance function are given. Estimates of distribution of some functionals from module of stationary Gaussian proper complex random processes are obtained. Behaviour of the module of stationary proper complex random processes at infinity is analysed.

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